

Data sheet for SINAMICS G120X

Article No.: 6SL3220-1YE40-0UB0

Client order no. : Order no. : Offer no. : Remarks :

Rated data				
Input				
	Number of phases	3 AC		
	Line voltage	380 480 V +10 %	-20 %	
	Line frequency	47 63 Hz		
	Rated voltage	400V IEC	480V NEC	
	Rated current (LO)	104.00 A	91.00 A	
	Rated current (HO)	94.00 A	80.00 A	
Output				
	Number of phases	3 AC		
	Rated voltage	400V IEC	480V NEC 1)	
	Rated power (LO)	55.00 kW	75.00 hp	
	Rated power (HO)	45.00 kW	60.00 hp	
	Rated current (LO)	110.00 A	96.00 A	
	Rated current (HO)	90.00 A	77.00 A	
	Rated current (IN)	113.00 A		
	Max. output current	149.00 A		
Pulse frequency		4 kHz		
Output frequency for vector control		0 200 Hz		
Οι	tput frequency for V/f control	0 550 Hz		
Overload capability				
Lavy Overland (LO)				

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time

General tech. specifications		
Power factor λ	0.90 0.95	
Offset factor $\cos\phi$	0.99	
Efficiency η	0.97	
Sound pressure level (1m)	70 dB	
Power loss 3)	1.730 kW	
Filter class (integrated)	Unfiltered	
EMC category (with accessories)	without	
Safety function "Safe Torque Off"	without SIRIUS device (e.g. via S7- 1500F)	

Communication

Communication USS, Modbus RTU, BACnet MS/TP



Item no. : Consignment no. : Project :

Inputs / outputs				
Standard digital inputs				
Number	6			
Switching level: 0 → 1	11 V			
Switching level: $1 \rightarrow 0$	5 V			
Max. inrush current	15 mA			
Fail-safe digital inputs				
Number	1			
Digital outputs				
Number as relay changeover contact	2			
Output (resistive load)	DC 30 V, 5.0 A			
Number as transistor	0			
Analog / digital inputs				
Analog / digital inputs Number	2 (Differential input)			
3 3 .	2 (Differential input) 10 bit			
Number				
Number Resolution				
Number Resolution Switching threshold as digital input	10 bit			
Number Resolution Switching threshold as digital input 0 → 1	10 bit 4 V			
Number Resolution Switching threshold as digital input $0 \rightarrow 1$ $1 \rightarrow 0$	10 bit 4 V			

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5\,^{\circ}\text{C}$

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



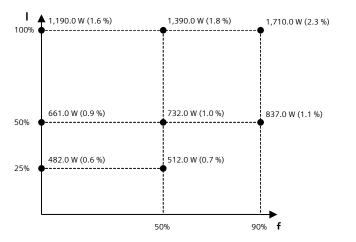
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Ambient conditions		
Standard board coating type	Class 3C2, according to IEC 60721-3-3: 2002	
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.083 m ³ /s (2.931 ft ³ /s)	
Installation altitude	1,000 m (3,280.84 ft)	
Ambient temperature		
Operation	-20 45 °C (-4 113 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-25 55 °C (-13 131 °F)	
Relative humidity		
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible	
Conn	ections	
Signal cable		
Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)	
Line side		
Version	screw-type terminal	
Conductor cross-section	25.00 70.00 mm ² (AWG 6 AWG 3/0)	
Motor end		
Version	Screw-type terminals	
Conductor cross-section	25.00 70.00 mm ² (AWG 6 AWG 3/0)	
DC link (for braking resistor)		
PE connection	Screw-type terminals	
Max. motor cable length		
Shielded	200 m (656.17 ft)	
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Mechanical data				
Degree of protection	IP20 / UL open type			
Frame size	FSE			
Net weight	27 kg (59.52 lb)			
Dimensions				
Width	275 mm (10.83 in)			
Height	551 mm (21.69 in)			
Depth	248 mm (9.76 in)			
Standards				
Compliance with standards	UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH			
CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC			

Converter losses to IEC61800-9-2*	
Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	47.9 %



The percentage values show the losses in relation to the rated apparent power of the converter

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*calculated values

 $^{^{1)}\}mbox{The output current}$ and HP ratings are valid for the voltage range 440V-480V

³⁾ Typical value. More information can be found in the element group "Converter losses to IEC 61800-9-2" in this datasheet.